# **Explanation of Station Keeping Analysis**

There are four plots included in this explanation to show the effects on the ability of the DP MODU to maintain station while disabling one quadrant of thrusters.

## The four plots are described as:

- 1. Plot C1-E1 System Intact (All thrusters operational) One-Year Return Environment
- 2. Plot C1-E4 System Intact (All thrusters operational) Normal Winter Storm
- Plot C3-E1 One Quadrant Disabled (Two Thrusters out of service) One-Year Return Environment
- 4. Plot C3-E4 One Quadrant Disabled (Two Thrusters out of service) Normal Winter Storm

### Environmental Criteria is defined as:

## One-Year Return:

- Current Speed = 0.6 knots
- Wind Speed = 26 knots
- Wave Height (Max) = 9 feet
- Vessel Draft = 55 feet

## **Normal Winter Storm:**

- Current Speed = 1.5 knots
- Wind Speed = 50 knots
- Wave Height (Max) = 19 feet
- Vessel Draft = 55 feet

## Plot Definitions:

- Solid Black Line = Forward Azimuth Heading Control
- Solid Blue Line = Aft Azimuth Heading Control
- Solid Red Line = Forward Power Position Control
- Solid Green Line = Aft Power Position Control
- X-axis = Percent Power Required
- Compass Axis = Incident Angle (direction the environment originates)
- Environment Note = All forces are collinear

## Plot C1-E1 Summary

- All 8 Thrusters in Service
- Environment is One-Year Return

- Black/Blue Lines overlap
- Reg/Green Lines overlap
- 10%-12% of Power is required for heading control
- 5% of Power is required for position control

## Plot C1-E4 Summary

- All 8 Thrusters in Service
- Environment is Normal Winter Storm
- 40% to 50% of Power is required for heading control
- 30% to 40% of Power is required for position control

## Plot C3-E1 Summary

- One Quadrant (Two Thrusters) are out of service
- Environment is One-Year Return
- 15% to 25% of power is required for heading control (depending upon incident angle)
- 5% to 12% of power is required for position control (depending upon incident angle)

## **Plot C3-E4 Summary**

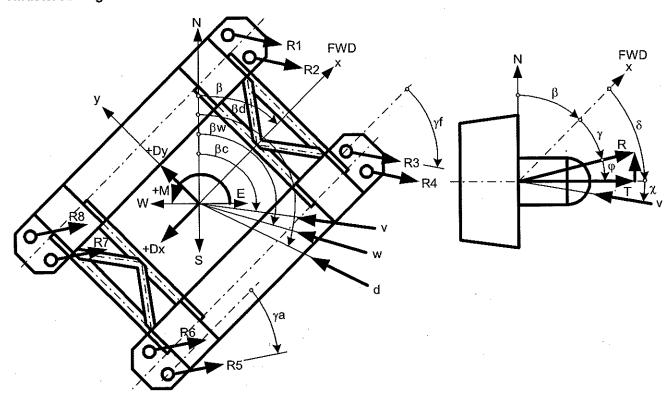
- One Quadrant (Two Thrusters) are out of service
- Environment is Normal Winter Storm
- 40% to 95% of power is required for heading control (depending upon incident angle)
- 30% to 100+% of power is required for position control (depending upon incident angle)

## Summary

The above information should demonstrate the effect disabling one quadrant of thrusters has on the ability of the vessel to maintain station. Any increase in the environment over the benign, one-year return criteria drastically increases power requirements to maintain station. Due to this, normal practice is to keep all quadrants in use as the vessel is less susceptible to incident angle of the environment.

Under normal conditions, we would not disable a quadrant of thrusters while connected to the sea floor as this causes undue risk to the environment and our asset.

## **Thruster Arrangement and Forces**



# **Thruster Location Coordinates, Thruster Status**

#### CCF = 1 Coordinates Thruster Status Thruster No. x [ft] y [ft] e [-] Note: If Thruster is in service 101 1 132 out of service e = 0 132 69 3 132 -69 -101 132 Power P0 = 3500 -132 -101 Thrust T0 = 116.7 -132 -69 Thrust Tv = 111.7 -132 69

# **Consideration of Cross Coupled Forces**

Note: With consideration of the cross coupled forces

Consideration of CTP = 0 Equal Thrust FWD and AFT

ower P0 = 3500 [HP] (nominal motor output)
hrust T0 = 116.7 [kips] at bollard pull condition
hrust Tv = 111.7 [kips] at current speed v

## **Environmental Data**

-132

v = 0.6	[knots] Current speed	
w = 26.0	[knots] Wind speed	
Hs = 9.0	[feet] Wave height	
Dft = 55.0	[feet] Vessel draft	
Admissible draft range		Dft = 23ft 65ft
Admissible wave height range		Hs = 0ft 40ff

101

bc = 90	[deg] Current angle
bw = 90	[deg] Wind angle
bd = 90	[deg] Wave angle

# Environmental Data Incident Angle

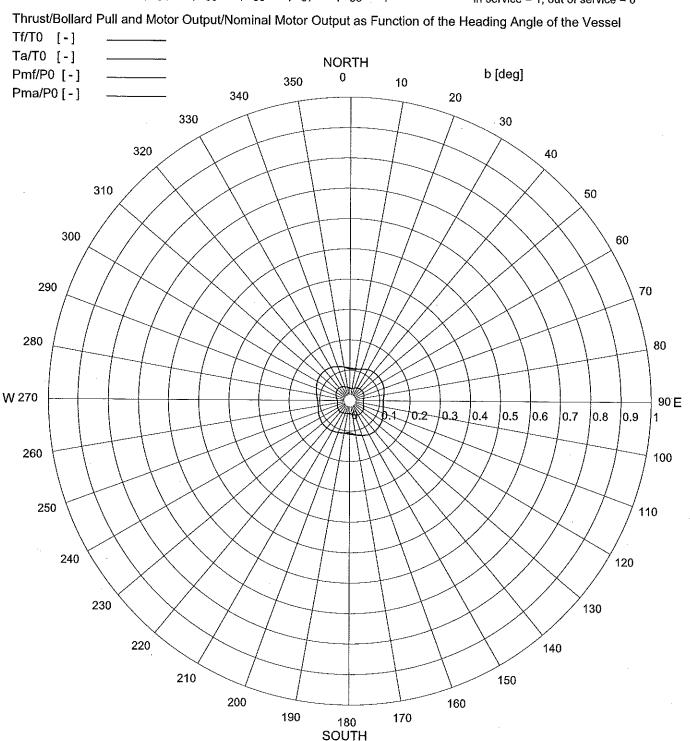
v = 0.6 [knots] Current speed bc = 90 [deg] Current angle w = 26.0 [knots] Wind speed bw = 90 [deg] Wind angle Hs = 9 [ft] Wave height bd = 90 [deg] Wave angle

Hs = 9 [ft] Wave height bd = 90 [deg] Wave angle

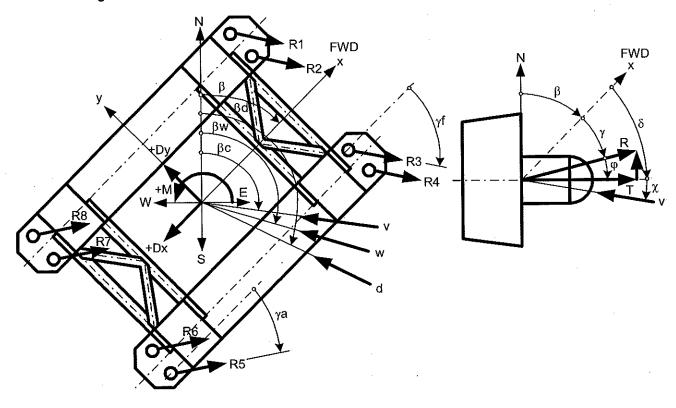
Dft = 55 [ft] Vessel draft Thruste

Dft = 55 [ft] Vessel draft Thruster No. : e1 = 1 e2 = 1 e3 = 1 e4 = 1 e5 = 1 e6 = 1 e7 = 1 e8 = 1 in service = 1.

in service = 1, out of service = 0



# **Thruster Arrangement and Forces**



# **Thruster Location Coordinates, Thruster Status**

#### **Consideration of Cross Coupled Forces** CCF = 1 Coordinates Thruster Status Note: If Thruster is Note: With consideration of the e [-] Thruster No. x [ft] y [ft] cross coupled forces in service 132 101 1 out of service e = 0 Consideration of CTP = 0 69 2 132 Equal Thrust FWD and AFT 3 132 -69 -101 132 4 [HP] (nominal motor output) Power P0 = 3500 -132 -101 Thrust T0 = 116.7 [kips] at bollard pull condition -132 -69 6 Thrust Tv = 104.9[kips] at current speed v -132 69 7 -132 101 1

## **Environmental Data**

v = 1.5	[knots] Current speed	
w = 50.0	[knots] Wind speed	
Hs = 19.0	[feet] Wave height	
Dft = 55.0	[feet] Vessel draft	
Admissible draft range		Dft = 23ft 65ft
Admissible wave height range		Hs = 0ft 40ff

bc = 90	[deg] Current angle
bw = 90	[deg] Wind angle
bd = 90	[deg] Wave angle

**Environmental Data** 

# Incident Angle

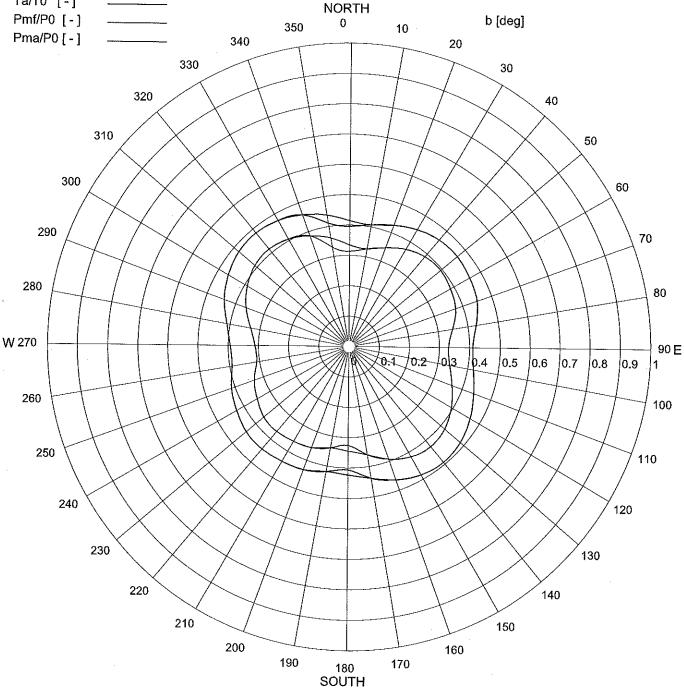
[knots] Current speed bc = 90[deg] Current angle 50.0 [knots] Wind speed bw = 90[deg] Wind angle Hs = 19

[ft] Wave height bd = 90[deg] Wave angle

Dft = 55[ft] Vessel draft Thruster No.: e1 = 1 e2 = 1 e3 = 1 e4 = 1 e5 = 1 e6 = 1 e7 = 1 e8 = 1 in service = 1, out of service = 0

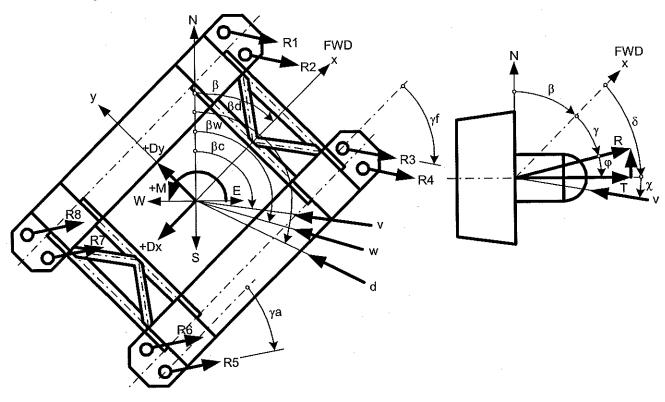
Thrust/Bollard Pull and Motor Output/Nominal Motor Output as Function of the Heading Angle of the Vessel





## PLOT C3-E1

# **Thruster Arrangement and Forces**



## **Thruster Location Coordinates, Thruster Status**

69

-69

-101

-101

-69

69

101

132

132

132

-132

-132

-132 -132

# Coordinates Thruster Status x [ft] y [ft] e [-] Note: If Thruster is in service e = 1132 101 0 out of service e = 0

Consideration of Cross Coupled Forces

CCF = 1

•	
Note:	With consideration of the
	cross coupled forces

Consideration of CTP = 0	
Equal Thrust FWD and AFT	

Power P0 = 3500	ſΗ

Thrust	T0 =	116.7
Thrust	Tv =	111.7

[kips] at bollard pull cond [kips] at current speed v

## **Environmental Data**

Thruster No.

1

2

3

5

6

7

v = 0.6	[knots] Current speed	
w = 26.0	[knots] Wind speed	
Hs = 9.0	[feet] Wave height	
Dft = 55.0	[feet] Vessel draft	
Admissible draft	range	Dft =

Dft = 23ft ... 65ft

Admissible wave height range Hs = 0ft ... 40ft

bc = 90	[deg] Current angle
bw = 90	[deg] Wind angle
bd = 90	[deg] Wave angle

## PLOT C3-E1

# Environmental Data Incident Angle

v = 0.6 [knots] Current speed bc = 90 [deg] Current angle w = 26.0 [knots] Wind speed bw = 90 [deg] Wind angle

Hs = 9 [ft] Wave height bd = 90 [deg] Wave angle

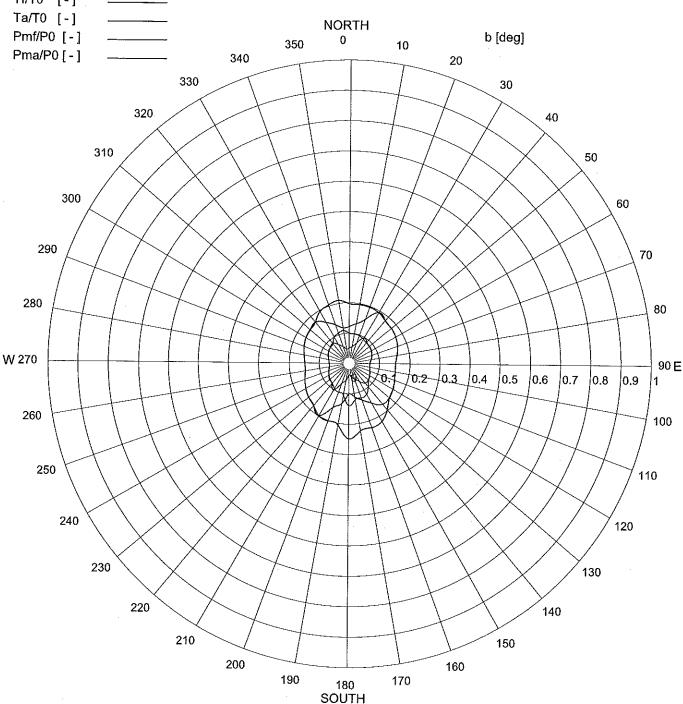
Dft = 55 [ft] Vessel draft
e1 = 0 e2 = 0 e3 = 1 e4 = 1 e5 = 1 e6 = 1 e7 = 1 e8 = 1

Thruster No.:
in service = 1,

e1 = 0 e2 = 0 e3 = 1 e4 = 1 e5 = 1 e6 = 1 e7 = 1 e8 = 1 in service = 1, out of service = 0

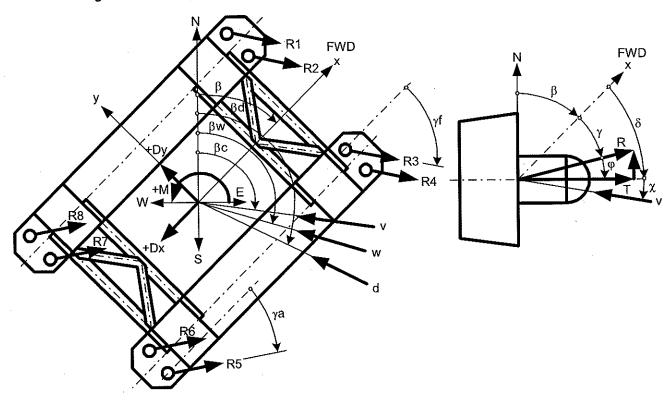
Thrust/Bollard Pull and Motor Output/Nominal Motor Output en Function of the Use of

Thrust/Bollard Pull and Motor Output/Nominal Motor Output as Function of the Heading Angle of the Vessel Tf/T0 [-]



PLOT C3-E4

# **Thruster Arrangement and Forces**



# **Thruster Location Coordinates, Thruster Status**

#### **Consideration of Cross Coupled Forces** CCF = 1Coordinates Thruster Status Note: With consideration of the Note: If Thruster is x [ft] y [ft] e [-] Thruster No. cross coupled forces in service 1 132 101 out of service e = 0 Consideration of CTP = 0 2 132 69 Equal Thrust FWD and AFT 3 132 -69 132 -101 4 Power P0 = 3500 [HP] (nominal motor output) -101 -132 [kips] at bollard pull condition Thrust T0 = 116.7 6 -132 -69 [kips] at current speed v Thrust Tv = 104.9-132 69 7 -132 101

## **Environmental Data**

v = 1.5	[knots] Current speed	
w = 50.0	[knots] Wind speed	
Hs = 19.0	[feet] Wave height	
Dft = 55.0	[feet] Vessel draft	
Admissible draft range		Dft = 23ft 65ft
Admissible wave height range		Hs = 0ft 40ft

bc = 90	[deg] Current angle
bw = 90	[deg] Wind angle
bd = 90	[deg] Wave angle

## PLOT C3-E4

Dft = 55

fft

# Environmental Data Incident Angle

v = 1.5 [knots] Current speed bc = 90 [deg] Current angle w = 50.0 [knots] Wind speed bw = 90 [deg] Wind angle Hs = 19 [ft] Wave height bd = 90 [deg] Wave angle

Vessel draft pd = 90 [deg] wave angle Thruster No.:

e1 = 0 e2 = 0 e3 = 1 e4 = 1 e5 = 1 e6 = 1 e7 = 1 e8 = 1 in service = 1, out of service = 0

Thrust/Bollard Pull and Motor Output/Nominal Motor Output as Function of the Heading Angle of the Vessel

